# KEYENCE



# Instruction Manual

CCD Laser Displacement Sensor *LK Series* 

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This is a class A (EN55011: EMI standard) product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.



#### Class 3B laser product

Do not directly look at or touch the laser beam or the laser beam reflected from a mirror-surfaced object. This may cause serious eye or skin injury.

# **SAFETY PRECAUTIONS**

This manual describes how to install the LK series as well as its operating procedures and precautions. Please read this manual carefully to get the best from your LK series.

# Safety precautions

# **Symbols**

The following symbols alert you to important messages. Be sure to read these messages carefully.



Failure to follow instructions may lead to injury. (electric shock, burn, etc.)



Failure to follow instructions may lead to product damage.

Note

Provides additional information on proper operation.

#### **General precautions**

- At startup and during operation, be sure to monitor the functions and performance of the LK series.
- We recommend that you take substantial safety measures to avoid any damage in the event a problem occurs.
- Do not open or modify the LK series or use it in any way other than described in the specifications.
- When the LK series is used in combination with other instruments, functions and performance may be degraded, depending on operating conditions and the surrounding environment.
- Do not use the LK series for the purpose of protecting the human body.

# 1. Classification

Model	LK-031	LK-081	LK-501	LK-503
FDA	Class II		Class IIIb	Class II
IEC 825-1 11.1993	Class 2		Class 3B	Class 2
DIN EN 60825-1 07.1994	Klasse 2		Klasse 3B	Klasse 2

# 2. Warning labels

- 1) Warning labels
- 2) Aperture label
- 3) Protective housing label

#### FDA Class II [LK-031/081]



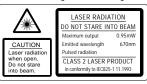
#### FDA Class II [LK-503]



#### FDA Class IIIb [LK-501]



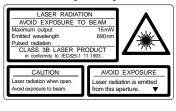
#### IEC Class 2 [LK-031/081]



#### IEC Class 2 [LK-503]



#### IEC Class 3B [LK-501]



#### IEC (French) Class 2 [LK-031/081]



# [LK-503]

IEC (French) Class 2



#### IEC (French) Class 3B **ILK-5011**



#### DIN Klasse 2 [LK-031/081]



#### DIN Klasse 2 [LK-503]



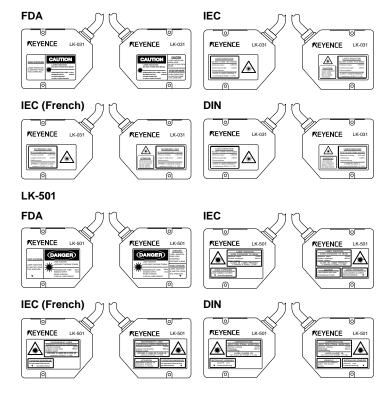
#### DIN Klasse 3B [LK-501]



# 3. Labels location

FDA Warning labels are attached to the sensor head as shown below. The IEC/DIN Warning labels are packaged with the LK series. Affix the Warning labels on the sensor head as shown below.

#### LK-031/081/503



# 4. Safety consideration

# 1) Class IIIb laser products



Use of controls or adjustments, or the performance of procedures other than those specified herein, may result in hazardous radiation exposure.

# **WARNING**

Follow the safety precautions below to ensure operator safety:

- Do not directly look at or touch the laser beam or the laser beam reflected from a mirror surfaced object. This may cause serious eye or skin injury.
- Operate the LK series only according to the procedures described in this instruction manual.

Otherwise, injury may occur due to exposure to the laser beam.

Do not disassemble the sensor head.

Laser emission from the LK series is not automatically stopped if the sensor head is disassembled. If you disassemble the sensor head for inspection or repair, you may be exposed to the laser beam. If the LK series malfunctions, contact KEYENCE immediately.

• Protective enclosure

We recommend that you install a protective enclosure around the sensor head to prevent any person from getting near the sensor head during operation.

Protective goggles

We recommend that you wear protective goggles when using the LK series.

- Stop laser emissions before cleaning the laser emission port.
   Failure to stop the laser emission may expose eyes or skin to the laser beam.
- · Check the laser beam path.

To prevent exposure to the laser beam due to specular or diffuse reflection, install a screen which offers the appropriate reflectance and temperature characteristics to interrupt the reflected laser beam. Do not install the LK series in such a way that the laser beam passes at eye height.

# 2) Class II laser products

# **A** CAUTION

Use of controls or adjustments, or the performance of procedures other than those specified herein, may result in hazardous radiation exposure.

The laser beam is not harmful to the skin. There is, therefore, no danger in exposing arms or hands to the beam. The only possible health hazard is in exposing the eyes to the laser beam. Damage to the eyes can occur if the operator stares directly into the beam.

# **WARNING**

Follow the safety precautions below to ensure operator safety:

 Operate the LK series only according to the procedures described in this instruction manual.

series malfunctions, contact KEYENCE immediately.

- Otherwise, injury may occur due to exposure to the laser beam.
- Do not disassemble the sensor head.
   Laser emission from the LK series is not automatically stopped if the sensor head is disassembled. If you disassemble the sensor head for inspection or repair, you may be exposed to the laser beam. If the LK
- Do not look directly at the laser beam.
   Looking directly at the laser beam may result in serious eye injury.
- Protective enclosure

We recommend that you install a protective enclosure around the sensor head to prevent any person from getting near the sensor head during operation.

· Protective goggles

We recommend that you wear protective goggles when using the LK series.

- Stop laser emissions before cleaning the laser emission port.
   Failure to stop the laser emission may expose eyes to the laser beam.
- · Check the laser beam path.

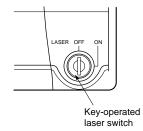
To prevent exposure to the laser beam due to specular or diffuse reflection, install a screen which offers the appropriate reflectance and temperature characteristics to interrupt the reflected laser beam. Do not install the LK series in such a way that the laser beam passes at eye height.

# 5. Safety features provided with the LK series

The LK series is provided with the following safety features. Make sure these features function correctly before operating.

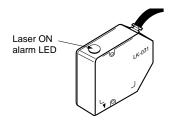
# ■ Key-operated laser switch

A key-operated switch controls the LK series laser. Remove the key when the laser is not in use.



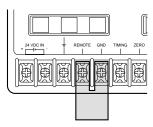
# ■ Laser ON alarm LED (Is ON during laser emission.)

After the key-operated laser switch is set to the ON position, the laser ON alarm LED flashes for approximately 3 seconds before laser emission. The LED lights during laser emission. The LED light can be checked through protective goggles.



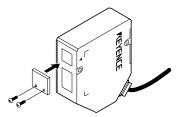
#### ■ Remote interlock terminal

Laser emission can be stopped by disconnecting the REMOTE terminal from the GND terminal.



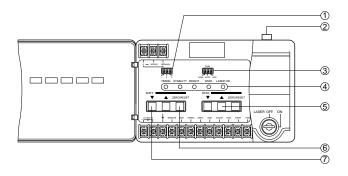
# ■ Laser beam shield (shutter) [with LK-501/503 only]

Laser emission is blocked by attaching the shutter.

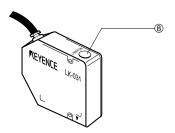


# **PART NAMES**

# Controller



#### Sensor head



#### ① DIP switches

Set alarm hold function, key-lock function, and averaging function.

#### (2) Sensor head connector

#### 3 Sensitivity setting switch

Changes the received light sensitivity according to the reflectance of the target. (\$\times\$ Refer to p. 15)

#### (4) Indicators

TIMING: Lights during synchronous (timing) input.

**STABILITY:** Lights yellow or green when a target is within the measuring range. Lights red when a target is out of the measuring range, or when the light quantity is insufficient or excessive.

BRIGHT: Lights when the light quantity is excessive.

DARK: Lights when the light quantity is insufficient.

LASER ON: Lights during laser emission.

#### ⑤ SPAN adjustment keys

Finely adjusts the inclination of the analog output.

#### 6 AUTO ZERO/RESET keys

Resets the analog output to 0 V (12 mA) at any point. Cancels AUTO ZERO function.

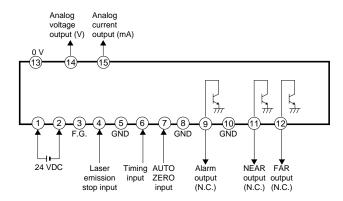
#### SHIFT adjustment key

Finely adjusts the 0-point position of the analog output.

#### ® Operation indicator

Lights yellow or green when a target is within the measuring range. Flashes yellow when a target is out of the measuring range, or when the light quantity is insufficient or excessive.

#### CONNECTIONS



#### 1), 2 Power supply input terminal

#### Frame grounding (F.G.) terminal Earth-ground this terminal.

#### 4 Laser emission stop input

Disconnecting this terminal from the GND terminal (\$, \$, \$) stops laser emission. Use this terminal in an emergency to stop laser emission.

#### 6 Synchronous (timing) input

Connecting this terminal to the GND terminal ( $(\S, @)$ ,  $(\emptyset)$ ) retains the analog output value just prior to the synchronous input, and stops laser emission.

#### AUTO ZERO input

Connecting this terminal to the GND terminal ( $\S$ ), (\$)) resets the analog output to 0 V (12 mA). The input is a one-shot input.

#### Alarm output (N.C.)

The output contact opens when measurement is impossible due to an insufficient or excessive light quantity, or due to the target being out of the measuring range. The output is normally closed.

#### (1) NEAR alarm output (N.C.)

The output contact opens when a target is positioned closer than the measuring range. The output is normally closed.

#### FAR alarm output (N.C.)

The output contact opens when a target is positioned further than the measuring range. The output is normally closed.

#### (13), (4) Analog voltage output

A voltage of  $\pm 5$  V ( $\pm 10$  V in LK-501/503's high-precision mode) relative to the full measurement range is output. +12 V is output when measuring is impossible.

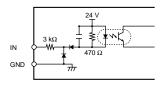
#### (3), (5) Analog current output

A current of 4 to 20 mA relative to the full measuring range is output. 31.2 mA is output when measuring is impossible.

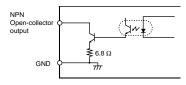
Note: The analog current remains at 0 mA over the measurement range with an analog voltage output of -7.5 V or less.

# INPUT/OUTPUT CIRCUIT

Input circuit (AUTO ZERO, synchronous, and laser emission stop)



#### Output circuit (Alarm, NEAR, and FAR)

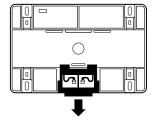


**Note:** Use a non-voltage contact to connect or disconnect the input terminals.

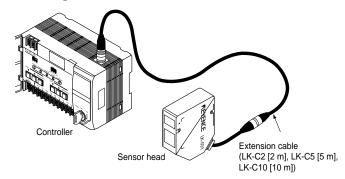
# **INSTALLATION**

#### Controller

The controller can be mounted to a DIN rail. When mounting or removing the controller, pull the claw at the bottom center in the direction of the arrow.



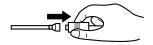
# Connecting sensor head and controller



Connect the sensor head to the extension cable(s), and the extension cable(s) to the controller as shown above.

To join the connectors, gently press them together and turn them to the right or left to locate the engagement position, then press until a click is heard.

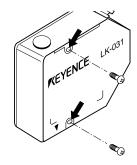
To remove the connectors, hold the connecting sleeve as shown on the right, and pull it out in the direction of the arrow.



#### INSTALLATION

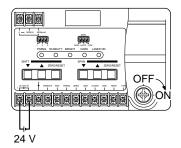
#### Sensor head

Secure the LK-031 and LK-081 with M4 screws, or the LK-501/503 with M5 screws using the two mounting holes indicated by the arrows.



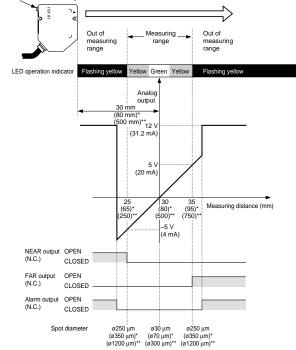
# **POWER-ON**

- 1. Provide a 24 VDC power supply to terminals No. 1 and 2.
- 2. Set the key-operated switch to the ON position. The laser beam is emitted from the sensor head and the unit is ready to perform measurement. (Connect the REMOTE and GND terminals with a shorting jumper.)



# OUTPUT CHARACTERISTICS AND LED INDICATOR [LK-031/081/501/503 IN LONG RANGE MODE]

Adjust the distance between the sensor head and target by checking the sensor head's LED operation indicator.



Data given in ( )\* applies to the LK-081.

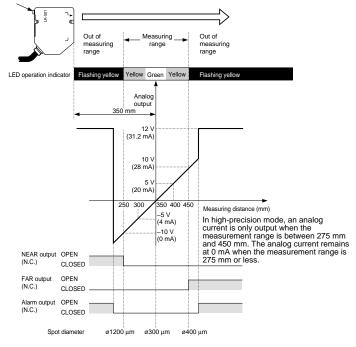
Data given in ( )\*\* applies to the LK-501/503 in long-range mode.

**Note 1:** The NEAR or FAR output turns on only when the target moves slowly from the inside to the outside of the measuring range.

**Note 2:** When measurement is affected by the scattered reflection of a mirrorsurfaced target, the operation indicator remains in the normal status, and the alarm output is not turned on even if the target is out of the measuring range.

# OUTPUT CHARACTERISTICS AND LED INDICATOR [LK-501/503 IN HIGH-PRECISION MODE]

Adjust the distance between the sensor head and target by checking the sensor head's LED operation indicator.



**Note 1:** The NEAR or FAR output turns on only when the target moves slowly from the inside to the outside of the measurement range. **Note 2:** When measurement is affected by scattered reflections from a mirror-surfaced target, the operation indicator shows normal status, and the alarm output is not turned on even if the target is out of the measurement range.

# **SETTING**

# **Measuring distance**

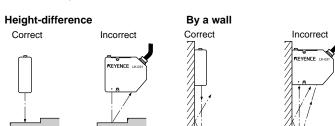
#### LK-031/081/501/503

To measure the thickness of a moving object, place the target close to the reference position where the spot diameter is smallest. This assures the most stable detection.

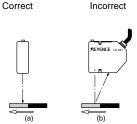


# Target shape and recommended setting

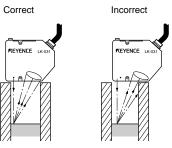
The LK series is less affected by the sensor head orientation by employing the CCD as the light-receiving element. For the following applications, however, mount the sensor head with the recommended orientation, if possible.



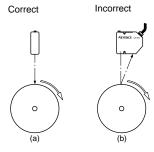
# Border of different color or luster



# Displacement in a hole



#### Moving object



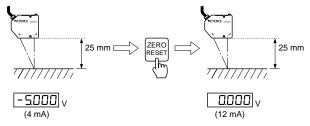
#### FUNCTIONS AUTO ZERO

#### **AUTO ZERO function**

Resets the output voltage to 0 V at the desired point within the measuring range.

Changing the zero position enables the output range to be set at either -10 to 0 V, or 0 to 10 V.

#### Example



#### **Canceling AUTO ZERO:**

Press the ZERO RESET key for approximately 2 seconds. AUTO ZERO is canceled and 0 V (12 mA) is output when the target is at the reference position.

#### **External input:**

Connecting the AUTO ZERO input terminal to the GND terminal sets the AUTO ZERO input.

# Relationship between the key-lock function and AUTO ZERO function

Property Refer to p. 16 for the key-lock function.

#### When FREE is set:

The value of the AUTO ZERO input is internally stored and retained even the power is turned off.

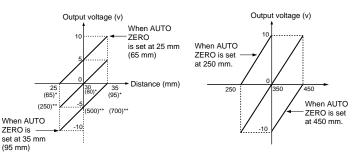
#### When LOCK is set:

The AUTO ZERO input is available only from the external input terminal. When the power is turned off, the value of the AUTO ZERO input is not stored, and the zero point is reset to the reference position.

**Note:** If the AUTO ZERO input is used frequently, set the key-lock function to LOCK, and set the AUTO ZERO externally.

# **AUTO ZERO position and output characteristics**

LK-031/081 LK-501/503 (Long-range mode) LK-501/503 (High-precision mode)



Data in ( )\* applies to the LK-081.

Data in ( )\*\* applies to the LK-501/503 in long-range mode.

**Note:** When the AUTO ZERO input is set immediately after the power is turned on, there may be a 10 mV error due to the temperature characteristics of the internal circuit. The error is gradually reduced and becomes 0 V in approximately 30 minutes.

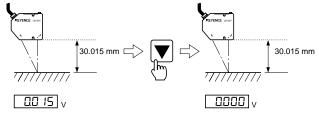
The temperature characteristics may cause low accuracy of the AUTO ZERO reset depending on the ambient temperature.

# **FUNCTIONS SHIFT/SPAN**

# Shift adjustment function



Adjusts the analog value zero point using the UP/DOWN keys for shift adjustment.



Holding down the UP/DOWN keys to change the shift value faster. Pressing the ZERO RESET key for 2 seconds cancels the shift adjustment value, and 0 V (12 mA) is output when the target is at the reference position.

#### ■ Shift adjustment range

LK-501/503 (Long-range mode)

Output voltage (V)

Output voltage (V)

12
10
10
10
10
10
Distance (mm)

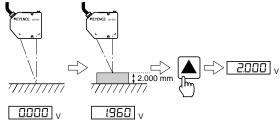
Data in ( )\* applies to the LK-081.

Data in ( )\*\* applies to the LK-501/503 in long-range mode.

# Span adjustment function



Adjusts the analog value inclination using the UP/DOWN keys for span adjustment. Use the span adjustment when the sensor head is tilted or the target surface condition affects the analog output characteristics.

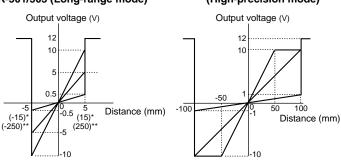


Value is inaccurate due to reflective property of the target surface.

Holding down the UP/DOWN keys to change the span value faster. Pressing the RESET key for 2 seconds cancels the span adjustment value, and the output characteristics are reset to the factory-set values.

#### ■ Span adjustment range LK-031/081 LK-501/503 (Long-range mode)

# LK-501/503 (High-precision mode)

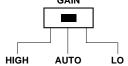


Data in ( )\* applies to the LK-081.

Data in ( )\*\* applies to the LK-501/503 in long-range mode.

# FUNCTIONS SENSITIVITY SETTING

Sets an appropriate sensitivity according to the change in target surface condition.



Set the sensitivity to AUTO for normal use.

#### AUTO:

Used to measure various objects: from objects with low reflectance such as black rubber, to ones with high reflectance such as metals.

**Note:** If the reflectance of the target changes greatly during a short cycle, the analog output may become unstable with the AUTO setting. In this case, set the sensitivity to HIGH or LO.

#### HIGH:

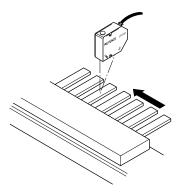
Fix the sensitivity to high. Used to measure a part with low reflectance (black) in the above condition.

#### LOW:

Fix the sensitivity to low. Used to measure a part with high reflectance in the above condition.

#### **Example: Measurement of pin warpage**

In the measurement of the warpage of moving pins, the reflectance of the pin and gap change greatly during a short cycle. To measure such a target, set the sensitivity setting switch to LO and measure only pins which have high reflectance.



Output waveform obtained with AUTO



Output waveform obtained with LO

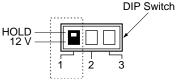


#### FUNCTIONS DIP SWITCHES

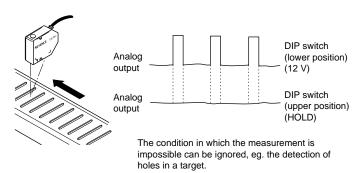
#### Alarm hold function

#### DIP switch 1

When DIP switch 1 is set to the upper position, the sensor does not produce the 12 V (31.2 mA) analog output during alarm output (range over/light quantity alarm), but retains the analog output value just prior to alarm output. This function is canceled when measurement is again possible.



When the DIP switch 1 is set to the lower position, the sensor produces the 12 V (31.2 mA) analog output during alarm output.

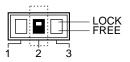


**Note:** The alarm output is produced in the alarm condition even if the alarm hold function is used.

# **Key-lock function**

#### DIP switch 2

When DIP switch 2 is set to the upper position, the sensor locks the shift adjustment, span adjustment, ZERO RESET and RESET keys so that each function cannot change. The shift (AUTO ZERO) and span values are fixed just prior to the lock operation.



Use this function to prevent the output voltage from being accidentally reset to zero.

When the DIP switch 2 is set to the lower position, the key-lock function is set to FREE and the lock operation is canceled.

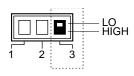
The AUTO ZERO input through the external input terminal is effective regardless of the LOCK or FREE setting. (However, with the LOCK set, the data will not be stored when the power is turned off.)

# **FUNCTIONS DIP SWITCHES**

# Response speed selection function

#### DIP switch 3

Set DIP switch 3 to select whether to output every measured value or the average of 8 measured values (moving average).



#### LO:

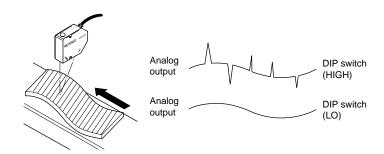
Outputs the value of the average of 8 measured values. Offers more stable detection when the luster of the target varies greatly.

#### HIGH:

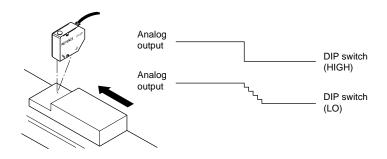
Outputs every measured value. Offers high-speed response when the target vibrates or moves quickly.

Average response time	LO	HIGH
LK-031	Approx. 4 ms	Approx. 0.5 ms (no averaging)
LK-081/LK-501/503	Approx. 8 ms	Approx. 1.0 ms (no averaging)

#### Example: When LO is set



#### Example: When HIGH is set



The HIGH setting is effective in detecting abrupt changes, such as height differences.

# FUNCTIONS MEASUREMENT MODE SELECTION [WITH LK-501/503 ONLY]

The LK-501/503 offers two measurement modes to be used according to the measurement conditions.

#### Long-range mode

Measures within a range of 250 to 750 mm.

Use long-range mode to mount the sensor head at a distance from the target, or to obtain a long measurement range.

#### **High-precision mode**

Measures within a range of 250 to 450 mm. Use high-precision mode to obtain high resolution.

#### ■ Mode selection

Hold down the UP key for the SHIFT adjustment, and turn the keyoperated laser switch from OFF to ON. This changes the measurement mode.

**Note:** The measurement mode is factory-set to long-range mode. The measurement mode is toggled every time the above operation is performed.

Long-range mode  $\rightarrow$  High-precision mode  $\rightarrow$  Long-range mode  $\rightarrow$  High-precision mode....

#### **■** Mode confirmation

Press the ZERO/RESET key for the SHIFT adjustment and the RESET key for the SPAN adjustment simultaneously. The indicators illuminate to show the current measurement mode.

#### When long-range mode is set:

Status of indicators

TIMING	STABILITY	BRIGHT	DARK	LASER ON	
Ϋ́	÷Κ	Ä	Ϋ́	Ϋ́	$\supset$

All five indicators illuminate.

#### When high-precision mode is set:

Status of indicators

	TIMING	STABILITY	BRIGHT	DARK	LASER ON	
$\subset$	0	0	Ϋ́	÷Κ	÷Ķ÷	$\supset$

Three indicators, BRIGHT, DARK, and LASER ON, illuminate.

# HINTS ON CORRECT USE

#### ■ Noise interference (The sensor head is case-grounded.)



Isolate the sensor cable and extension cable(s) from high-tension lines or power lines, otherwise the sensor may malfunction or the laser diode may deteriorate due to noise interference.

- If noise is present at the surface where the sensor head is mounted, install insulator between the mounting surface and the sensor head.
- Earth-ground the frame grounding terminal.



Do not connect the sensor head while the controller is turned on. The sensor head may be damaged.

#### ■ Compatibility

The LK series controller and sensor head have been calibrated in pairs. Be sure to use a sensor head and controller having the same serial number, otherwise the values given in the specifications cannot be attained.

#### **■** Environment



Keep the sensor head free of water or oil. Any substance that refracts light may cause unstable measurement.

Do not allow extraneous light to enter the lens of the sensor head directly.

\* When highly accurate measurement is required, attach shielding to the sensor head. If extraneous light enters the lens when no target is present, use a synchronous input to ignore it.

#### ■ Ambient light

Although up to 10,000 lux ambient light is allowed by the specifications, avoid using the sensor near lighting equipment that emits light in recurring pulses, if possible. If the sensor must be positioned near such equipment, minimize the effect by using a light shielding plate.

#### ■ Warm-up

Allow approximately 30 minutes after the power is turned on before using the LK series. The measurement value may gradually fluctuate because the circuit is not stable immediately after the power is turned on.

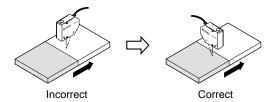
#### ■ Cable extension

Keep the sensor head cable as short as possible to prevent noise interference. (Less than 35 m)

Extension cables: LK-C2 (2 m), LK-C5 (5 m), and LK-C10 (10 m)

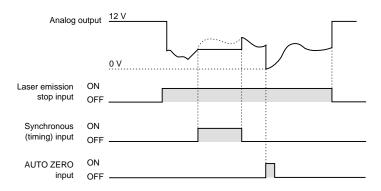
#### ■ Sensor head orientation

When a target consists of different colored portions or different materials separated by a border, measurement error may result depending on the orientation of the sensor head. To minimize measurement deviation, install the sensor head parallel to the border line, as shown below.



# **INPUT CHARACTERISTICS**

# **Timing diagram**

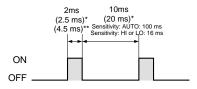


- Laser emission only starts approximately 2 seconds after the laser emission stop input terminal is connected.
- While the timing input is connected, laser emission stops. The analog output will hold the last value before the timing input signal turns on.

# Minimum input time

Data in ( )\* applies to the LK-081. Data in ( )\*\* applies to the LK-501/503.

#### Synchronous (timing) input

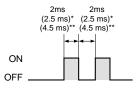


**Note:** The analog output is retained for the following amount of time after disconnection of the synchronous input terminal.

LK-031: Approx. 10 ms LK-081: Approx. 20 ms

LK-501/503 (Sensitivity: AUTO): Approx. 100 ms LK-501/503 (Sensitivity: HI or LO): Approx. 16 ms

#### **AUTO ZERO input**



**Note:** The analog output is retained approximately 10 ms after the synchronous input terminal is disconnected.

# **SPECIFICATIONS**

Model Sensor head Controller		Sensor head	LK-031	LK-081	LK-501/	/LK-503		
		LK-2001	LK-2101	LK-2501/	LK-2503			
Measurement mode		_	_	Long-range	High-precision			
Referen	nce distance		30 mm	80 mm	500 mm	350 mm		
Measur	ing range		±5 mm	±15 mm	±250 mm	±100 mm		
Light so	ource		Visible red semiconductor laser					
	Maximum out	tput	0.95 mW		LK-501: 15 mW, LK-503: 0.95 mW			
		FDA	3 to 482 μs 3 to 994 μs		3 to 9	94 μs		
	Pulse duration	IEC	3 to 482 μs	3 to 994 μs	3 to 9	94 μs		
	uuration	DIN EN 60825-1 07.1994	3 to 482 μs	3 to 994 μs	3 to 9	94 μs		
	Wavelength		670		690			
		FDA	Clas	ss II	Class IIIb (LK-501)	, ,		
	Class	IEC	Clas	ss 2	Class 3b (LK-501)	, Class 2 (LK-503)		
		DIN EN 60825-1 07.1994	Klas		Klasse 3b (LK-501)	, Klasse 2 (LK-503)		
Spot dia	ameter		Approx. 30 μm (at reference distance)	Approx. 70 μm (at reference distance)	Approx. 0.3 mm dia. (at reference distance)	Approx. 0.7 mm dia. (at reference distance)		
Linearit	ty			±0.1%	of F.S. <sup>1.</sup>			
Resolut	tion		1 μm ².	3 μm <sup>2.</sup>	50 μm <sup>2.</sup>	10 μm <sup>2.</sup>		
		Voltage	±5 V (1 mm/V)	±5 V (3 mm/V)	±5 V (50 μm/mV)	±10 V (10 μm/mV) <sup>3.</sup>		
Analog output Impedance		Impedance	100 Ω					
		Current	4 to 20 mA (350 $\Omega$ max.) $^{3.4.}$					
Alarm o	output		NPN open-collector 100 mA (40 V) max. (N.C.) Residual voltage 1 V max. <sup>3</sup>					
Samplin	ng cycle		512 µs 1024 µs					
Other fu	unctions		AUTO ZERO, Alarm hold, GAIN selection, Response speed selection, Span/Shift adjustment					
Power s	supply		24 VDC ±10% Ripple (p-p): 10 % max.					
Current	consumption	1	400 mA max.					
Temper	ature	Sensor head	0.01% of F.S./°C 0.02% of F.S./°C			f F.S./°C		
fluctuation Controller			0.01% of F.S./°C					
Enclosu	ure rating		IP-67					
Ambien	nt light		Incandescent or fluorescent lamp: 10,000 lux max. 5.					
Ambient Sensor head			0 to 50 °C (32 to 122 °F), No freezing					
temperature Controller			0 to 50 °C (32 to 122 °F), No freezing					
Relative humidity			35 to 85%, No condensation					
Vibration			10 to 55 Hz, 1.5 mm double amplitude in X, Y, and Z directions, 2 hours respectively					
Materia		Sensor head	Aluminum die-cast					
Controller			Polycarbonate					
Weight		Sensor head	Approx. 260 g	Approx. 385 g	Approx	. 700 g		
(includi	ing cable)	Controller		Appro	x. 515 g			

Linearity was obtained using KEYENCE's standard target (white ceramic block gauge).
 Resolution was obtained using KEYENCE's analog sensor controller (RD-50) with the number of averaging measurements set to 64. Note: The ripple of the analog output may be 1 mV or more due to common mode noise when observed with an oscilloscope or high-speed A/D conversion board.

<sup>3.</sup> When measurement is impossible, 12 V (31.2 mA) is output.

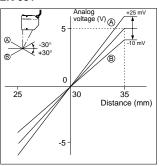
<sup>4.</sup> The analog current output is 4 to 20 mA over the measurement range with an analog voltage output of  $\pm 5$  V.

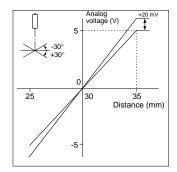
# **CHARACTERISTICS**

# **Angle characteristics**

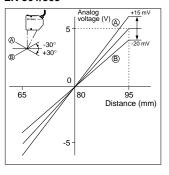
Changes the span of the analog output when a white ceramic target is tilted by  $\pm 30^\circ$  (Typical)

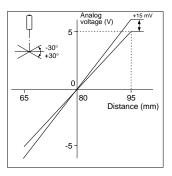
#### LK-031



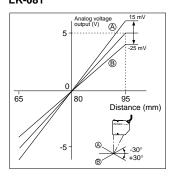


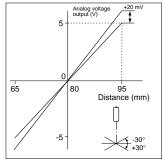
#### LK-501/503





#### LK-081

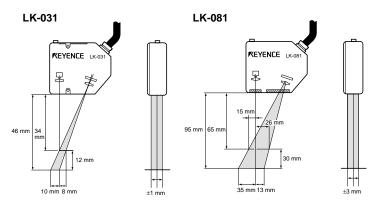


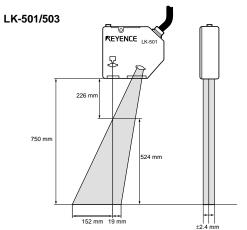


# **MUTUAL INTERFERENCE**

# Interference range

Interference will occur only when the beam spot of another sensor is positioned inside of the shadowed area.



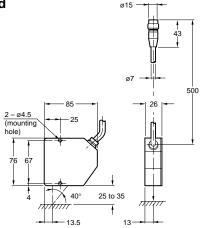


# **DIMENSIONS**

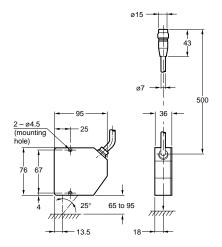
Unit: mm

#### Sensor head

LK-031

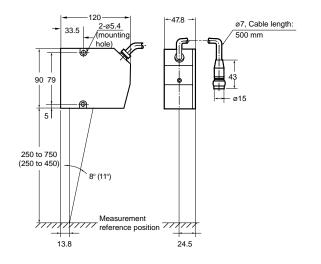


LK-081

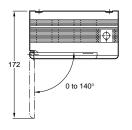


**DIMENSIONS**Unit: mm

#### LK-501/503

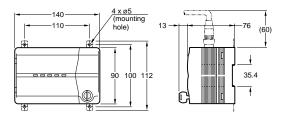


# Controller LK-2001/2101/2501/2503



#### Extension cable

Cable length (m)	Model
2	LK-C2
5	LK-C5
10	LK-C10



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